

# Score-Based Generative Modeling through Stochastic Differential Equations

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## ABSTRACT

- We perturb data to noise with a fixed stochastic differential equation (SDE), and learn to reverse it for sample generation. The reverse SDE can be obtained by estimating the time-dependent gradient field (aka. score function) of the perturbed data distribution.
- We achieve outstanding sample quality: state-of-the-art FID and Inception scores on CIFAR-10, high fidelity generation of 1024x1024 images.
- The SDE framework allows exact likelihood computation. We obtain the state-of-the-art likelihood on uniformly dequantized CIFAR-10 images, without maximum likelihood training.
- We can perform controllable generation without re-training models, and demonstrate applications in class-conditional generation, image inpainting and colorization.

Code:



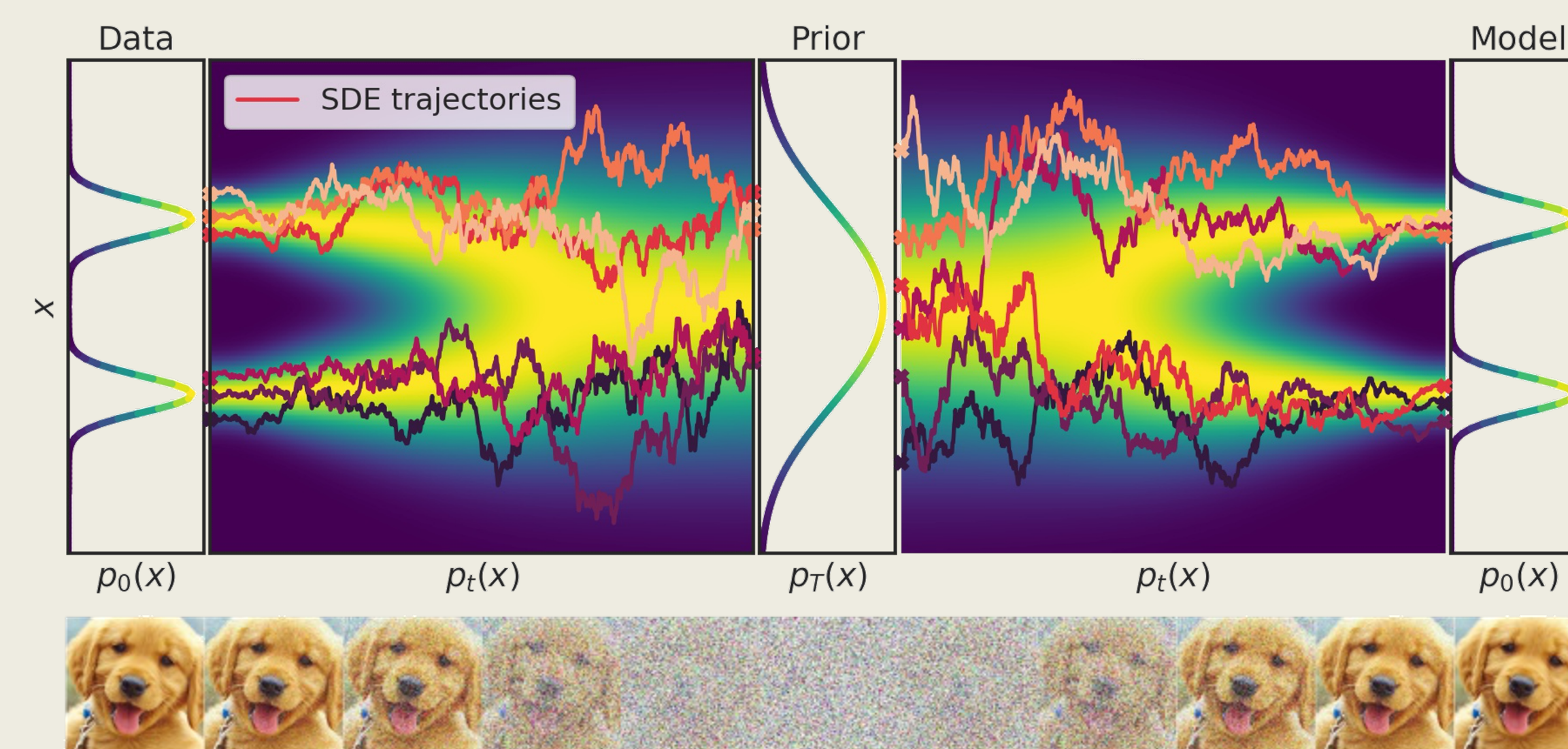
## Generative Modeling with SDEs

Stochastic differential equation (SDE):

$$dx = \underbrace{f(x, t) dt}_{\text{Deterministic drift}} + \underbrace{g(t) dw}_{\text{Stochastic diffusion}}$$

Brownian motion

Perturbing data with a fixed SDE, and reverse it for generative modeling



The reverse-time SDE:

$$dx = [f(x, t) - g^2(t) \nabla_x \log p_t(x)] dt + g(t) dw$$

Score function of  $p_t(x)$

- Must be solved in the reverse time direction
- Requires estimating score functions at all time steps.

Learning to reverse the SDE:

- Time-dependent score-based model

$$s_{\theta}(\cdot, t) : \mathbb{R}^d \rightarrow \mathbb{R}^d$$

- Goal:  $s_{\theta^*}(x, t) \approx \nabla_x \log p_t(x)$

Training objective:

$$\min_{\theta} \mathbb{E}_{t \sim \mathcal{U}(0, T)} \mathbb{E}_{x \sim p_t(x)} [\lambda(t) \|s_{\theta}(x, t) - \nabla_x \log p_t(x)\|_2^2]$$

- Score matching (Hyvarinen 2005)
  - Denosing score matching (Vincent 2010)
  - Sliced score matching (Song et al., 2019)

- Estimated reverse-time SDE

$$dx = [f(x, t) - g^2(t) s_{\theta^*}(x, t)] dt + g(t) dw$$

## Solving Reverse SDEs for Sampling

Numerical SDE solvers:

- Example: Euler-Maruyama method

Initialize  $t = T, x \sim p_T(x)$

Repeat until  $t = 0$

$$\begin{cases} \Delta x \leftarrow [f(x, t) - g^2(t) s_{\theta^*}(x, t)] \Delta t + g(t) z \\ x \leftarrow x + \Delta x \\ t \leftarrow t + \Delta t \\ z \sim \mathcal{N}(0, |\Delta t| I) \end{cases}$$

- Example: Reverse diffusion method (see paper)

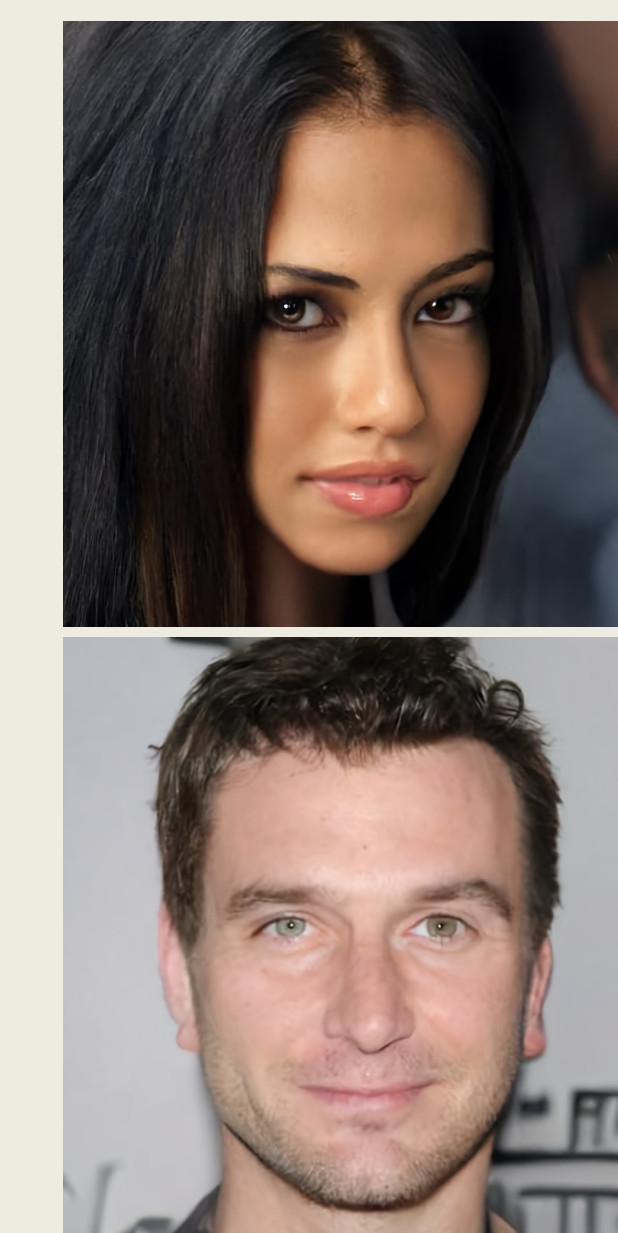
Predictor-Corrector methods:

- Improves numerical SDE solvers with MCMC, at the cost of more computation and more hyperparameters.

Experimental results:

CIFAR-10 sample quality		
Model	FID↓	IS↑
<b>Conditional</b>		
BigGAN (Brock et al., 2018)	14.73	9.22
StyleGAN2-ADA (Karras et al., 2020a)	<b>2.42</b>	<b>10.14</b>
<b>Unconditional</b>		
StyleGAN2-ADA (Karras et al., 2020a)	2.92	9.83
NCSN (Song & Ermon, 2019)	25.32	8.87 ± .12
NCSNv2 (Song & Ermon, 2020)	10.87	8.40 ± .07
DDPM (Ho et al., 2020)	3.17	9.46 ± .11
DDPM++	2.78	9.64
DDPM++ cont. (VP)	2.55	9.58
DDPM++ cont. (sub-VP)	2.61	9.56
DDPM++ cont. (deep, VP)	2.41	9.68
DDPM++ cont. (deep, sub-VP)	2.41	9.57
NCSN++	2.45	9.73
NCSN++ cont. (VE)	2.38	9.83
NCSN++ cont. (deep, VE)	<b>2.20</b>	<b>9.89</b>

CelebA-HQ 1024px samples



- Probability flow ODE:

$$dx = \left[ f(x, t) - \frac{1}{2} g^2(t) \nabla_x \log p_t(x) \right] dt$$

Score function of  $p_t(x) \approx s_{\theta^*}(x, t)$

Can sample from the same distribution by solving the ODE instead of the SDE.

Exact likelihood computation:

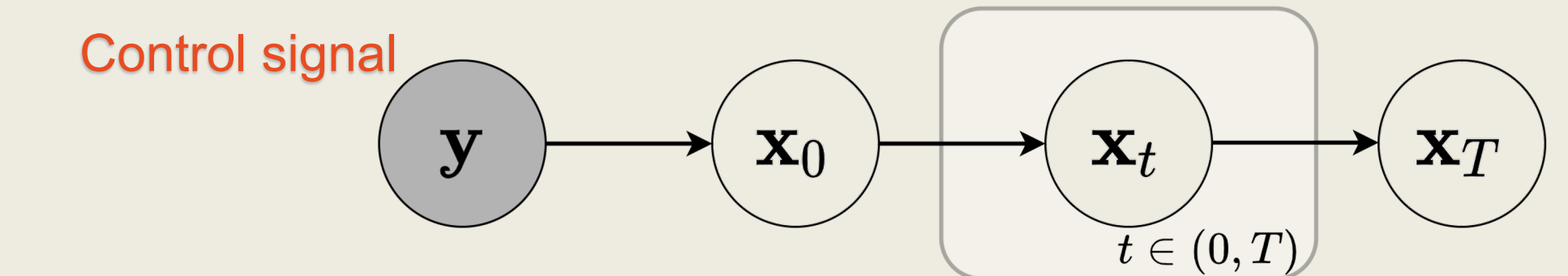
Model	NLL Test ↓	FID ↓
RealNVP (Dinh et al., 2016)	3.49	-
iResNet (Behrmann et al., 2019)	3.45	-
Glow (Kingma & Dhariwal, 2018)	3.35	-
MintNet (Song et al., 2019b)	3.32	-
Residual Flow (Chen et al., 2019)	3.28	46.37
FFJORD (Grathwohl et al., 2018)	3.40	-
Flow++ (Ho et al., 2019)	3.29	-
DDPM (L) (Ho et al., 2020)	≤ 3.70*	13.51
DDPM (L <sub>sample</sub> ) (Ho et al., 2020)	≤ 3.75*	3.17
DDPM	3.28	3.37
DDPM cont. (VP)	3.21	3.69
DDPM cont. (sub-VP)	3.05	3.56
DDPM++ cont. (VP)	3.16	3.93
DDPM++ cont. (sub-VP)	3.02	3.16
DDPM++ cont. (deep, VP)	3.13	3.08
DDPM++ cont. (deep, sub-VP)	<b>2.99</b>	<b>2.92</b>

$$\log p_T(z) \xrightarrow{\int} \log p_0(x)$$

Instantaneous change-of-variable formula (Chen et al. 2018)

## Controllable Generation

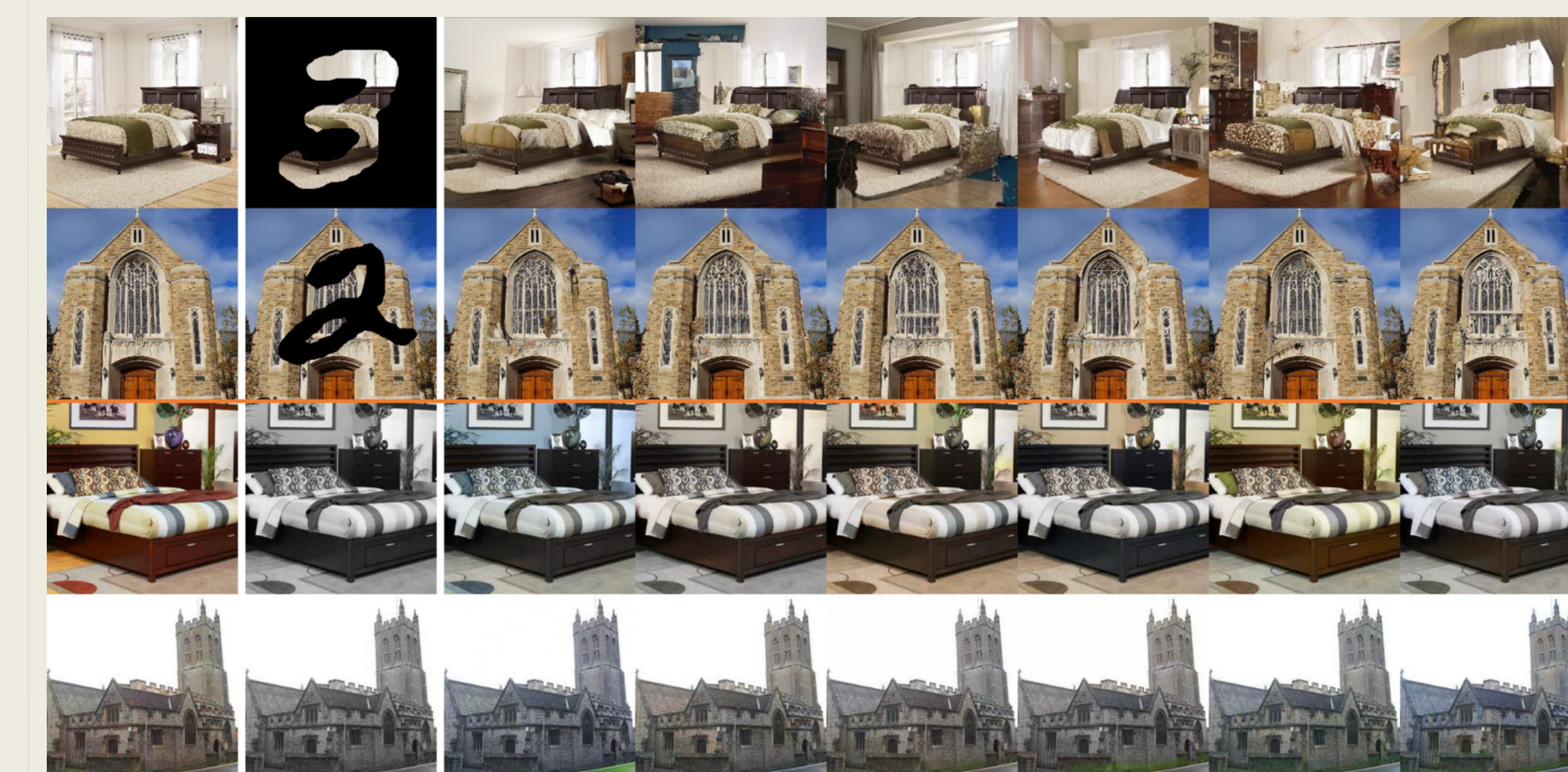
We can perform conditional generation with an unconditional score-based model. No need of re-training.



Reverse for controllable generation

$$\nabla_x \log p_t(x | y) = \underbrace{\nabla_x \log p_t(x)}_{\text{unconditional score, Trained w/o } y} + \underbrace{\nabla_x \log p_t(y | x)}_{\text{specified with domain knowledge}}$$

Image inpainting and colorization results:



## Probability Flow ODEs

Turning the SDE into an ODE with the same  $p_t(x)$

